



Klever Neo The brains behind it all.

Product Specification

The next generation in the growing dynasty of SMART Control Boxes by KLEVER, the Klever Neo is a confident evolution of mechatronic technology: its slim, low-profile housing facilitating total freedom in design, featuring an integrated, highly sensitive collision detection system. Renowned European quality and design, this revolutionary product represents the best value all-in-one Control Box on the market today.

kleverdesk.co.nz

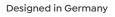


Features

- 240 W output power.
- · Cost-effective SMPS.
- Ultra-efficient 0.1 W standby power consumption.
- Office furniture as low as < 0.1W reducing CO2 emissions to a minimum.
- 1,000 desks in standby = 100watt light bulb.
- Improved driving dynamics: increased responsiveness & smooth start/stop.
- Built in light barrier technology.
- · Integrated collision sensor with high sensitivity.
- Sit/stand memory for Basic Hand Controls.
- Compatibility for standalone/mobile desk solutions.









Powerful Anti-Collision Protection System



20 Year Warranty



C Tick Tested to AU/NZ electrical standards.



Technical Data

Rated input current	2 A
Rated frequency	50-60 Hz
Rated input voltage	220-240 VAC
Rated output power	240 W
Standby power consumption	0.1 W
Duty cycle	2 Min. ON (120W) / 18 Min. OFF
	or 0.5 Min. (240 W), 0.5 Min (120W) / 9 Min. OFF
Dimensions (I* x w x h)	188.3 mm x 84.5 mm x 35.0 mm (7.874 " x 3.328 " x 1.376 ")
Compatibility	Visit Klever for a full list of compatible products.
Degree of protection (IEC 60529)	IP 20
Applicable standards	RoHS 2011/65/EU REACH regulation (EG) Nr. 1907/2006 EMV 2014/30/EU LVD
	directive 2014/35/EG Eco-Design directive 2009/125/ EG Machinery directive 2006/42/EC

Configuration Overview

- 1. Hand Controls
- 2. Klever Neo Box





As shown in the below, connect related parts, including control box, handset, extension cable and power cord etc. and fasten with cable clips.

- 1. Hand Controls
- 2. Klever Neo Box
- 3. AC Input Port (Power Cable)
- 4. DC/Com Port
- 5. Motor Port 1 (M1)
- 6. Motor Port 2 (M2)

